

CMS Forward Pixels Geometry Simulation

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For the CMS Forward Pixel Collaboration

**X Pisa 2006
Meeting**
Frontier Detectors
for Frontier Physics



Where to find information

➤ B-tau Physics Group

- <http://cmsdoc.cern.ch/cms/Physics/btau/management/top/btau.html>

➤ Tracker Simulation and Geometry

- **Coordinators:** **Filippo Ambroglini** (University of Perugia, Italy)
Neeti Parashar (Purdue University Calumet, USA)

➤ Pixel offline group

- <https://uimon.cern.ch/twiki/bin/view/CMS/PixelOfflineSoftware>
- **Coordinator:** **Vincenzo Chiochia** (University of Zurich)

➤ LPC Simulation Group

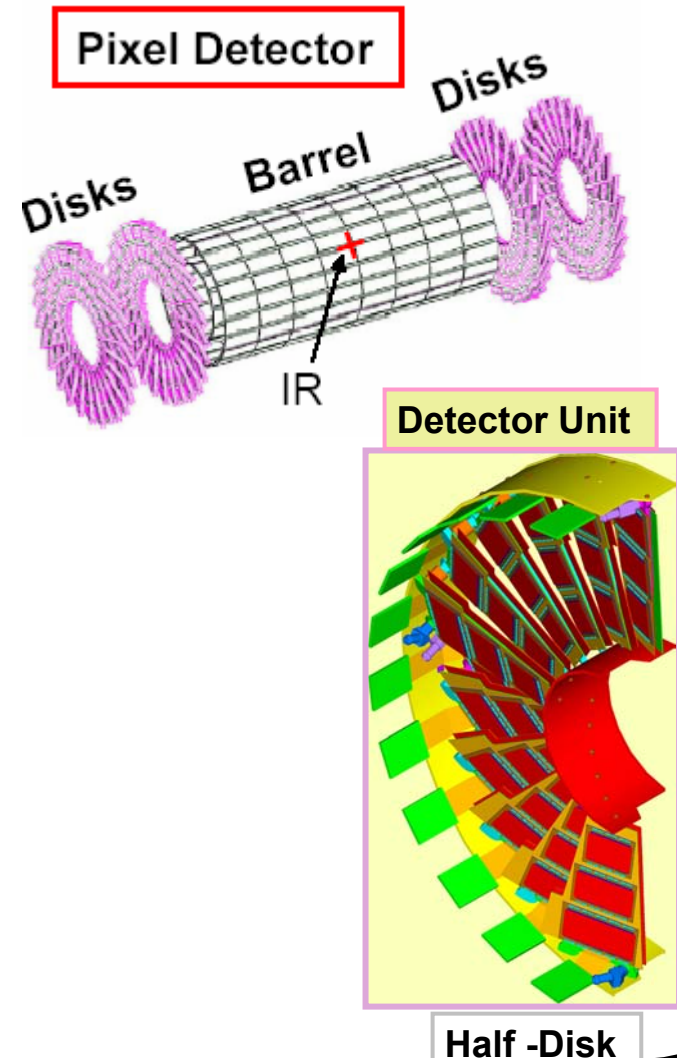
- http://www.uscms.org/LPC/lpc_simul/lpc_simulation.html
- **Coordinators:** **Daniel Elvira** (Fermilab, USA)
Harry Cheung (Fermilab USA)

Institutions

- **Purdue University Calumet, Indiana, USA**
 - **Neeti Parashar: Coordinator**
 - **Vesna Cuplov: Post-doctoral fellow**
- **Kansas State University, Kansas, USA**
 - **Dmitry Onoprienko: Post-doctoral fellow**
- **University of Puerto Rico, Puerto Rico, USA**
 - **Xingtao Huang: Post-doctoral fellow**
- **Northwestern University, Illinois, USA**
 - **Victoria Martin: Post-doctoral fellow**
- **University of Colorado, Colorado, USA**
 - **Max Bunce: Graduate student**

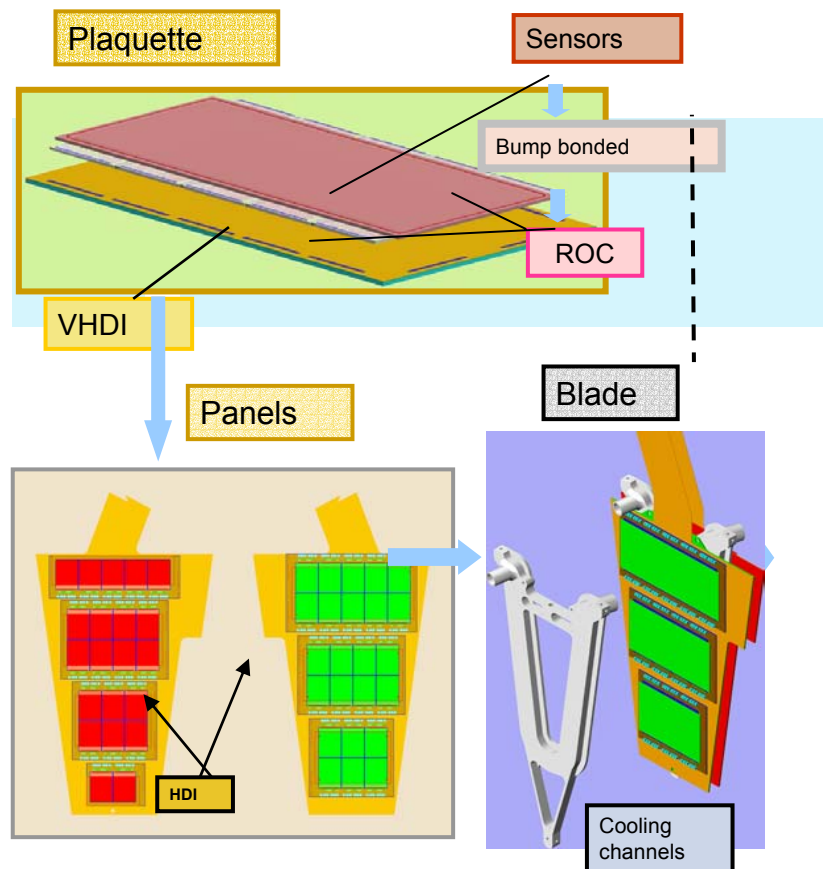
Forward Pixel Detector

- Complex design
- 4 circular disks (in pink)
- Inner radius = 6 cm
- Outer radius = 15 cm
- η from 1.5 to 2.25
- Each disk includes
24 wedge shaped blades
 - Turbine like geometry
 - Each blade is rotated 20° around their radial symmetry axis to increase charge sharing among pixels
 - Provides a hit resolution of $\sim 15 \mu\text{m}$

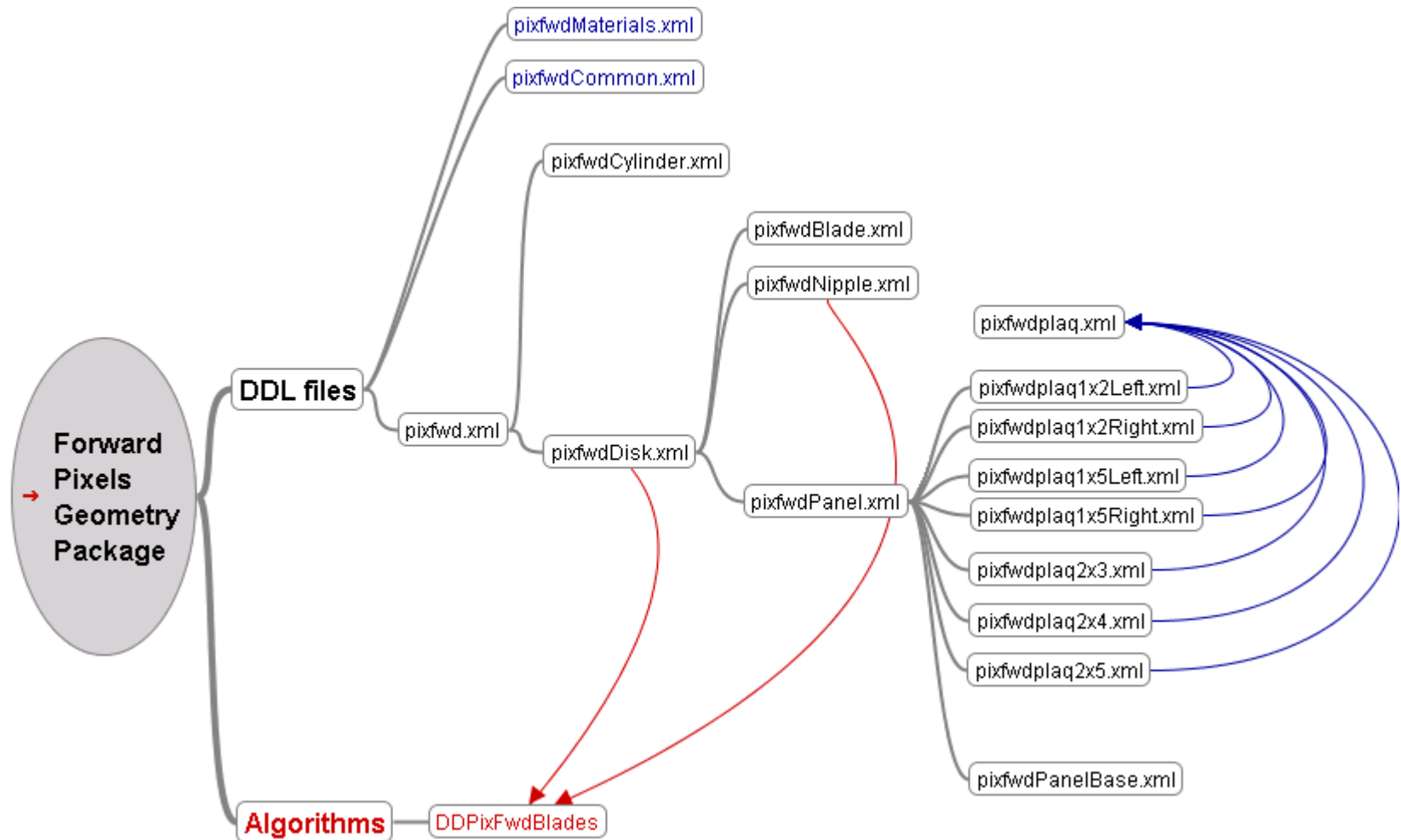


Details of Forward Pixel Disks

- Each blade has a set of 45 readout chips (ROC)
 - 5 different types
 - 1x5
 - 2x5
 - 2x4
 - 2x3
 - 1x2
 - Arranged in 7 different arrays on the two sides of the blade
 - An array of ROCs is bump bonded to a corresponding array of silicon sensors on top of it and thus forms a sandwich



Package Structure



Features

- Replaced old geometry description
- The new geometry is written in XML (eXtensive Markup Language)
- Based on DDD interface (Detector Description Database)
- Conforms to the latest mechanical drawings of the components
- Complete and fully tested successfully for simulation
- In use by the collaboration